# oscar@oscarfrias.com Brooklyn, NY www.oscarfrias.com

# OSCAR FRIAS

### **SKILLS**

### **EXPERIENCE**

### Machine Design:

 Mechanisms, structures, machine elements, stepper motors, trade studies

### Part Development:

- Injection Molding, machining and sheet metal
- Material selection
- FMEA, DFM, GD&T and Tolerance Analysis
- Testing, DOE
- FEA and analysisbased design

## CAD modeling:

 Solid and surface modeling in SolidWorks

## Programming:

 Processing, Arduino, VBA, NodeJS

## Prototyping:

 Manual & CNC machining, Rapid prototyping, welding, forging, composites, vacuum forming

## OCTOBER 2018 - PRESENT

## **PRINCIPAL ENGINEER, PENSA**

- Technical lead for the DIWire family of CNC wire bending machines
- Develop accurate and affordable, desktop-sized, CNC wire bending machines and their tooling from concept to market
- Manage the manufacturing team and the software development team
- Lead and mentor junior engineers for client-based projects

# OCTOBER 2015 – OCTOBER 2018 SENIOR DESIGN ENGINEER, PENSA

- Designing, prototyping, testing and delivering mechanical and electromechanical systems for products like a CNC wire bending machine, a robotic trash chute, a vending machine, a stroller, a baby monitor and other consumer and industrial products across a range of markets, developing them from concept to production-ready
- Managing client relationships and communications, and closely collaborating with multidisciplinary teams to ensure client and customer input is translated into requirements

## **AUGUST 2013 - SEPTEMBER 2015**

# PRODUCT DEVELOPMENT ENGINEER, UNILIFE

- Designed, developed and tested four novel, mechanically-actuated reconstitution syringe platforms, from conceptualization to production-equivalent devices
- Defined engineering specifications based on user-exerted forces and risk analysis results

### **MAY 2012 - JULY 2013**

## **RESEARCH ENGINEER, CARNEGIE MELLON UNIVERSITY / ASTROBOTIC**

 Manufactured, integrated and tested Earth-demonstration prototypes of the Polaris rover, its lunar excavator payload, and other mobile robotic exploration platforms

## **EDUCATION**

## MASTER OF PRODUCT DEVELOPMENT, 2012 - CARNEGIE MELLON UNIVERSITY

BS MECHANICAL ENGINEERING, 2006 - UNIVERSIDAD IBEROAMERICANA, MEXICO CITY

## **COURSES**

- Launchspace Space Vehicle Mechanisms, elements of successful design. Santa Clara, CA. May 3rd, 2016
- AAMI Human Factors for Medical Devices training, Alexandria VA.
   March 2015

### **AWARDS**

DELPHI 2012 Innovation Competition (Awarded 1<sup>st</sup> Place) – Carnegie Mellon Developed a vehicle alignment system that allowed drivers to accurately park an electric vehicle over a wireless charging pad with a precision of +/- 1" on their first attempt

### **LEADERSHIP**

- Mentor for Girls Of Steel First Robotics team, Fall 2012 Summer 2013 CMU FRC
- Engineering intern coordinator, 2016 present PENSA